



# Real-time Needle Steering in Response to Rolling Vein Deformation by a 9-DOF Image-Guided Autonomous Venipuncture Robot

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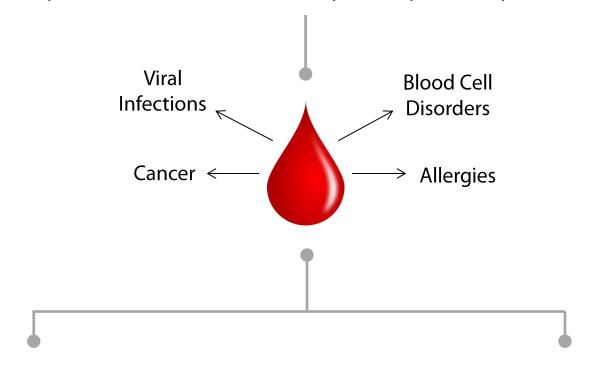


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# Venipuncture | Cornerstone of Modern Medicine

## Most common medical routine performed in the world

**9/10** patients admitted to the hospital require venipuncture<sup>[1,2]</sup>



**#1** Cause of Patient Injury<sup>[3]</sup>

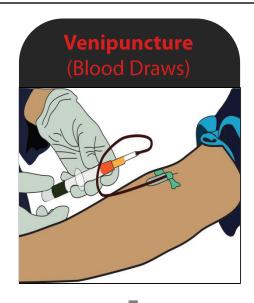
- 1B failed sticks per year

**#1** Cause of Clinician Injury<sup>[4]</sup>

- 1M sharps injuries per year



## Medical Robots | Diagnostic Testing Integration







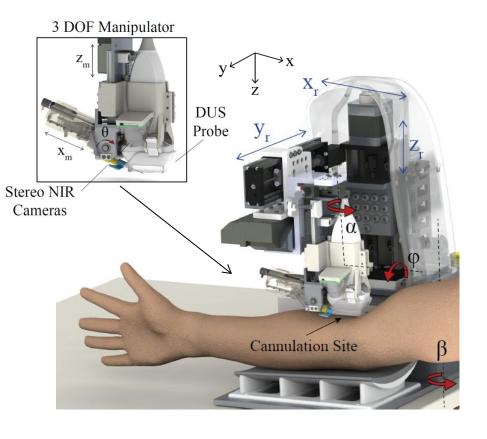


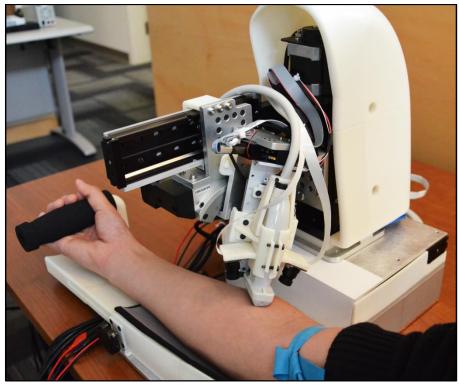




## Venipuncture Robot | The VenousPro™

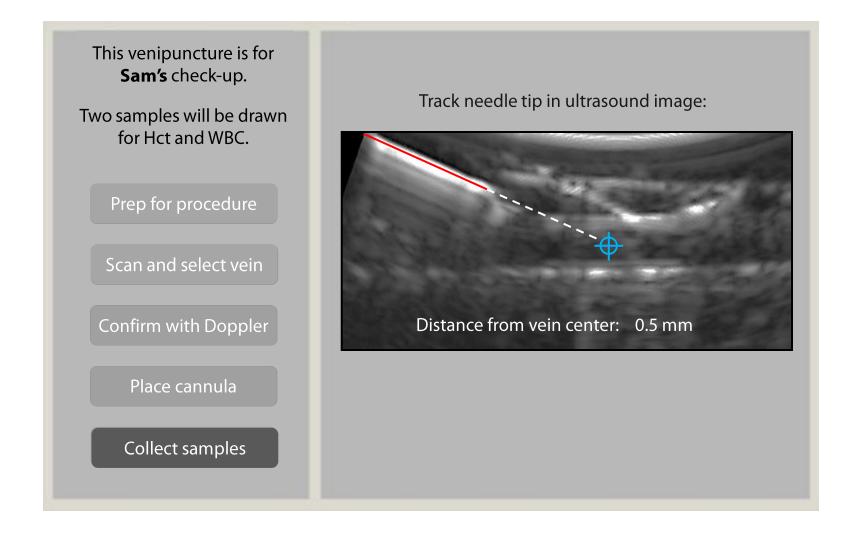
A portable, image-guided medical robot that improves the quality, safety, and cost-effectiveness of venous access in a fully automated fashion





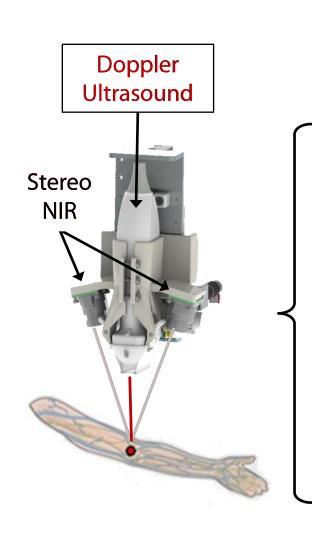


## Graphical User Interface | Clinical Protocol





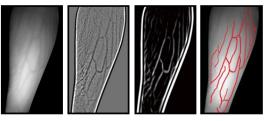
## Bimodal Imaging | Near-infrared & Ultrasound



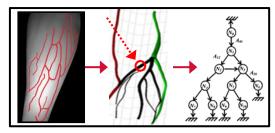
### 3D Near IR

(Coarse imaging)

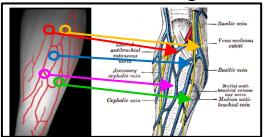
Vein Segmentation



3D Stereo Reconstruction

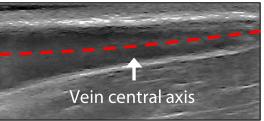


Vein Structure Recognition

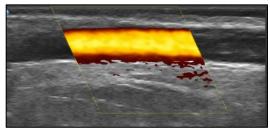


<u>Ultrasound</u> (Localized imaging)

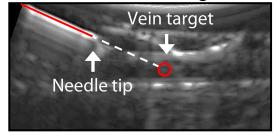
**Vessel Wall Tracking** 



**Blood Flow Detection** 

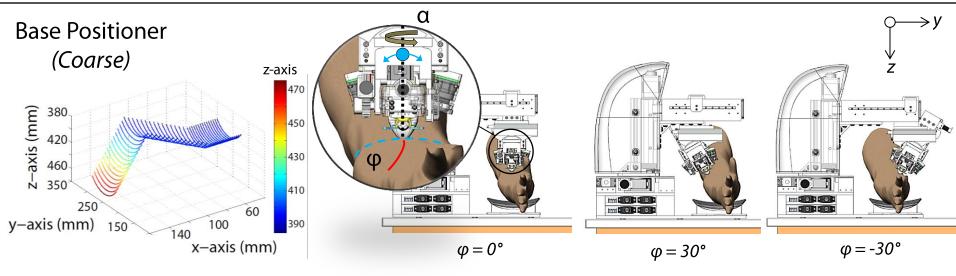


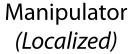
**Needle Tracking** 

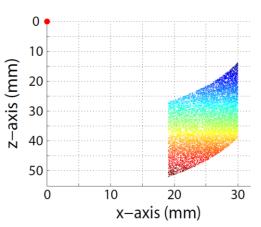


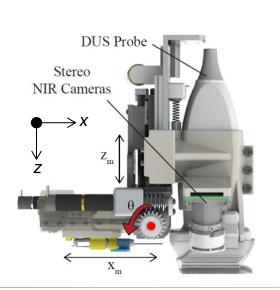


## Robotic System | Gantry & Manipulator

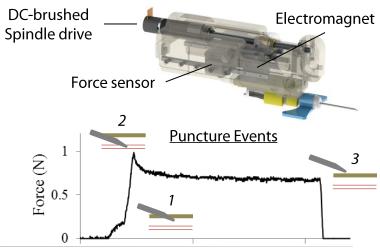






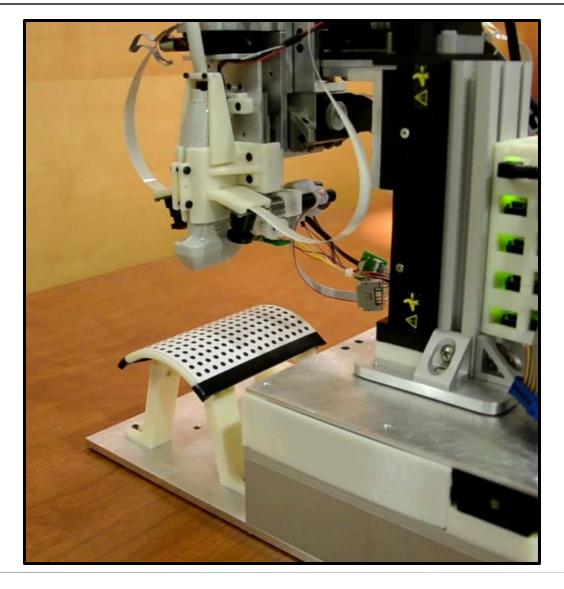


### Needle Insertion Mechanism





# Robotic System | Motion Testing

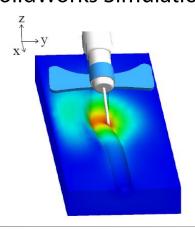




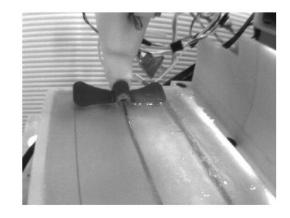
## *In vitro* Phantom Testing | Methods

- Simulations and in vitro phantoms were developed to investigate three needle insertion conditions:
  - 1. On-axis needle aligned with medial axis of vein
    - Ideal venipuncture
  - 2. Off-axis slip –slip at the interface between the needle and vein
    - Seen in patients with poorly anchored or rolling veins
  - 3. Off-axis no-slip
    - Seen in patients with stiff, hardened veins

#### SolidWorks Simulation



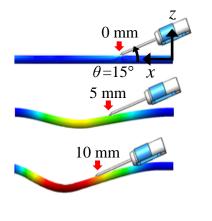
#### *In vitro* Phantom Cannulation

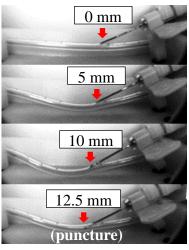




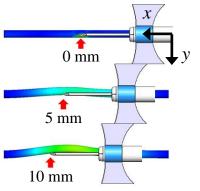
## *In vitro* Phantom Testing | Results

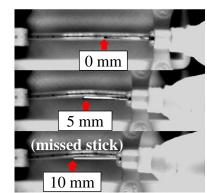
### On-axis (side view)



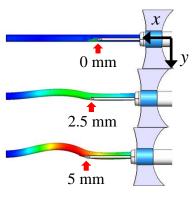


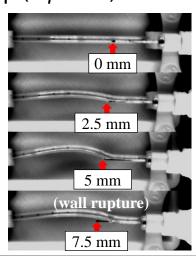
Off-axis slip (top view)



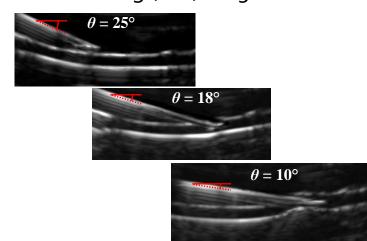


Off-axis no slip (top view)





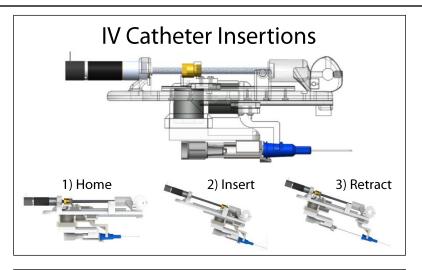
### Needle Steering (side, longitudinal view)

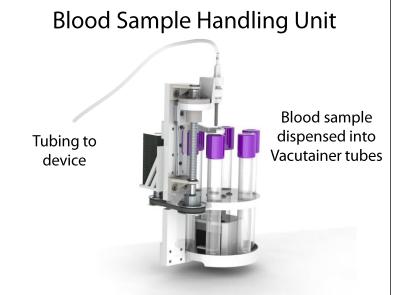


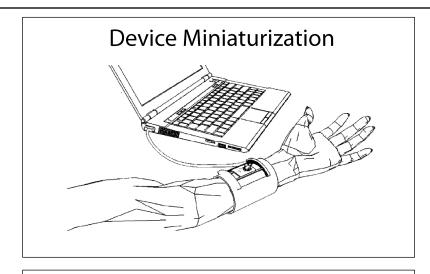


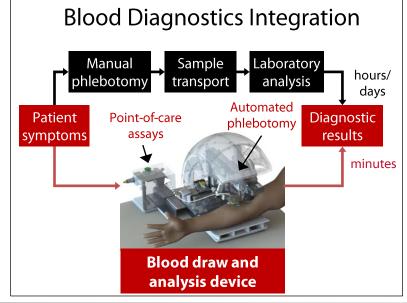
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# Future Directions | Extend Clinical Functionality











## Acknowledgments

### Collaborators

- Rutgers University, Dept. of Biomedical Engineering
- Rutgers (Robert Wood Johnson) Medical School



















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